

C&ESAR 2025 by DGA 32nd Computer & Electronics Security Application Rendezvous



TRUST-AWARE VERTICAL INTRUSION DETECTION FOR IOT VIA EVOLUTIONARY GRAPH NEURAL NETWORKS (V-IDS)

MYRIA BOUHADDI AND KAMEL ADI

COMPUTER SECURITY RESEARCH LABORATORY, UNIVERSITY OF QUEBEC IN OUTAOUAIS, GATINEAU, QUEBEC, CANADA

MYRIA.BOUHADDI@UQO.CA, KAMEL.ADI@UQO.CA



OUTLINE



CONTEXT AND MOTIVATION

Problem statement

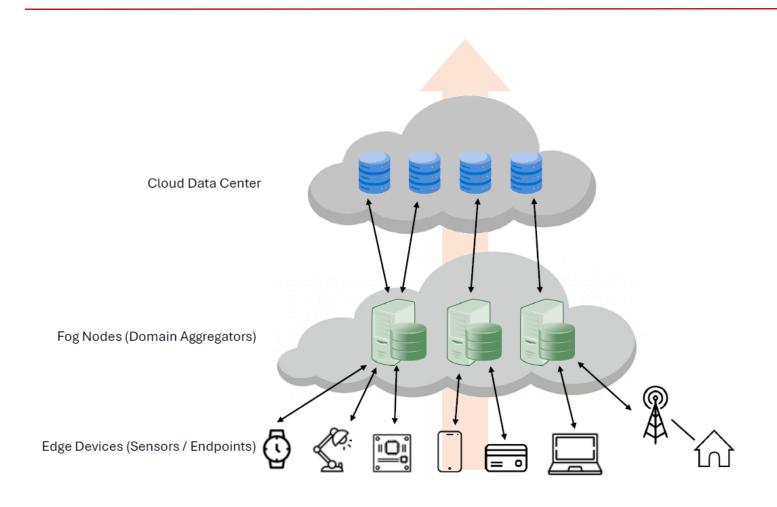
Proposed framework

Experimental evaluation

CONLUSION AND FUTURE WORK

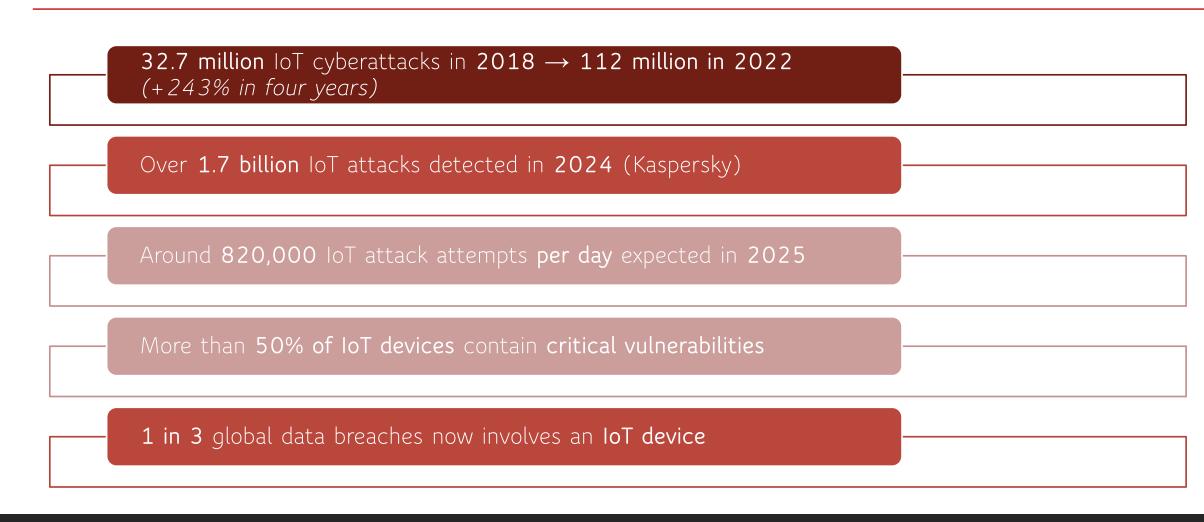
CONTEXT AND MOTIVATION:

FROM SMART HOMES TO SMART CITIES, AND NEW THREATS



"The same device that measures temperature can, tomorrow, be used to exfiltrate industrial secrets."

IOT ATTACKS ARE RAPIDLY INCREASING



IOT SECURITY WEAKNESSES AND EMERGING ATTACK VECTORS



Weak security defaults: default passwords, outdated firmware



Resource constraints: limited CPU/RAM \rightarrow weak/no encryption



Insecure protocols: MQTT, CoAP, UPnP, Telnet



Poor patching & maintenance: long-lasting exploitable flaws



Layered architecture: edge-fog-cloud blind spots



High heterogeneity: diverse devices, inconsistent security

Why Existing IDS Fail in Modern IoT Environments

Traditional IDS are flat, centralized, or focus only on single-layer events.

No global correlation across Edge-Fog-Cloud → multi-stage attacks stay hidden.

Existing GNNbased IDS use static topologies and fixed trust weights. They assume all nodes are equally reliable – even compromised ones.

Result:
fragmented
visibility, high
false positives,
delayed or missed
detection.

TOWARD ADAPTIVE VERTICAL DETECTION AND TRUST REASONING

Correlates alerts across Edge, Fog, and Cloud layers

→ enabling true multi-level IoT visibility

Integrates a dynamic trust mechanism

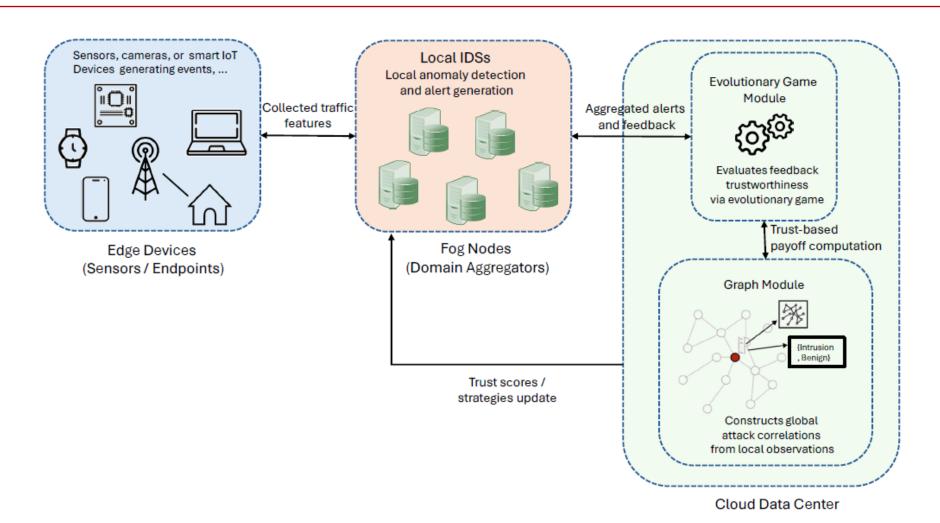
→ based on evolutionary game theory

Injects trust into a Graph Neural Network

→ for structural and temporal reasoning

Remains robust under adversarial and noisy conditions

A VERTICAL VIEW OF INTRUSION DETECTION



LOCAL DETECTION & METRIC EXTRACTION AT FOG NODES

• Each Fog node F_i monitors its Edge devices \mathcal{E}_i and extracts structured security metrics from raw detection events:

$$\phi_i(t) = igl[A_i(t), \ H_i(t), \ \Delta_i(t), \ R_i(t)igr]$$

Where:

- A_i -Anomaly intensity Average anomaly score across all events in $\mathcal{D}_i(t)$.
- H_i Event-type entropy Diversity of observed event types (Shannon entropy).
- Δ_i -Temporal dispersion Std deviation of inter-arrival times between events.
- R_i -Detection rate

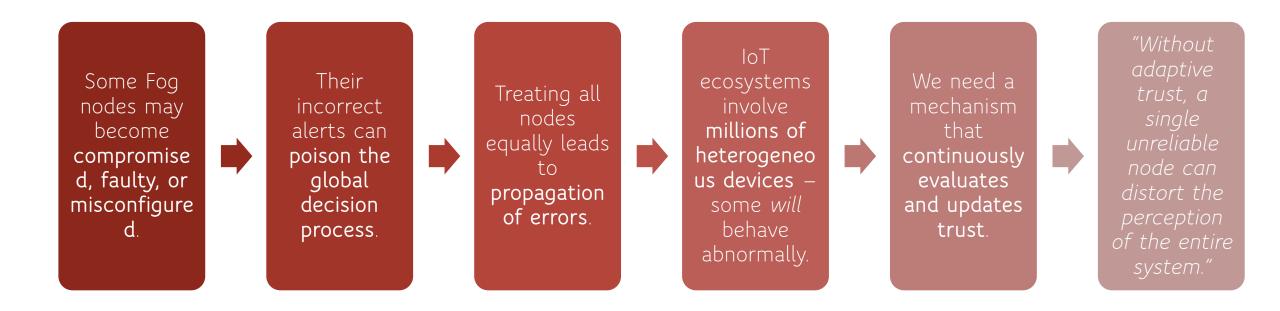
 Number of events per device per time window.

GLOBAL FUSION AT CLOUD LEVEL

Step 2 - Global Correlation using a Graph Neural Network (GNN)

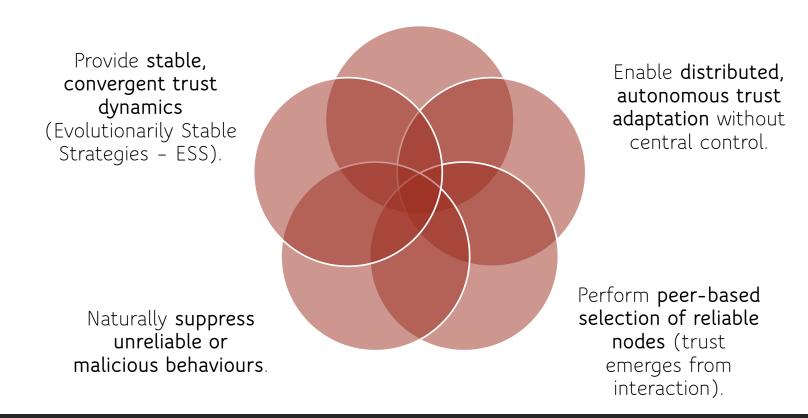
- · The cloud constructs a graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ from all Fog nodes.
- Nodes = Fog entities; Edges encode connectivity or behavioural similarity.
- \cdot Initial edge weights w_{ij} reflect <code>baseline trust</code> / <code>communication links</code>.
- $\cdot \to \mathsf{At}$ this stage, we have the global structure... but trust is still static.

WHY WE NEED ADAPTIVE TRUST BETWEEN NODES



THE POWER OF EVOLUTIONARY DYNAMICS IN CYBERSECURITY

Capture **temporal consistency** in node behaviour.



INSPIRATION FROM NATURE: EVOLUTIONARY ADAPTATION FOR TRUST

Nodes behave like agents in a population. Honest / cooperative behaviour → reinforced. Unreliable or inconsistent behaviour \rightarrow penalized and loses influence. Replicator Dynamics adjusts trust levels based on performance over time. "Trust evolves – it is not assigned once and for all."

EVOLUTIONARY GAME THEORY FOR TRUST MODELING

- Nodes act as players adapting their strategies over time.
- Fitness = consistency & correctness of their detections.
- Cooperative (honest) nodes → higher payoff → trust increases.
- Unreliable nodes \rightarrow lower payoff \rightarrow trust decays automatically.
- Replicator Dynamics adjust trust levels based on performance.
- Trust becomes an emergent, self-adjusting property not a fixed rule.

FROM UTILITY TO EVOLUTIONARY DYNAMICS

$$lacksquare ext{Node utility:} \quad u_i = \sum_{j \in \mathcal{N}(i)} w_{ij} \operatorname{sim}(arphi_i, arphi_j)$$

- lacktriangledown Average utility: $ar{u}=x_H u_H + x_U u_U$
- lacktriangle Replicator equation: $\dot{x}_s = x_s \left(u_s ar{u}
 ight)$
- lacksquare Node replicator coefficient: $r_i = u_i ar{u}$

INTEGRATING TRUST INTO THE GNN

Step 3 – Trust-Weighted Message Passing

We incorporate the trust scores into the GNN message-passing process:

$$ilde{arphi}_i = r_i \cdot arphi_i, \qquad ilde{w}_{ij} = r_i \cdot r_j \cdot w_{ij}$$

$$h_i^{(l+1)} = \sigma \left(\sum_{j \in \mathcal{N}(i)} ilde{w}_{ij} \, W^{(l)} h_j^{(l)}
ight)$$

We have:

- ullet High-trust nodes ullet stronger influence in the graph.
- Low-trust or inconsistent nodes \rightarrow attenuated messages.
- The GNN progressively filters out unreliable contributors.

"Trust acts as an adaptive volume control on each node's voice in the graph."

COMPLETE ALGORITHM FLOW

STEP 4 – END-TO-END VERTICAL IDS PIPELINE



Edge → Fog: local data collection + lightweight anomaly metrics



Fog \rightarrow Cloud: transmit summary vectors $\phi_i(t)$



Compute node utilities ui + trust/replicator coefficients ri



Construct a trust-weighted graph for GNN reasoning



Run GNN inference → fuse alerts across layers



Output global intrusion decisions with confidence scores

ADVERSARIAL SCENARIOS

EXPERIMENTAL EVALUATION: GOALS & METHODOLOGY

Assess robustness of the Vertical IDS under

- noisy environments
- · compromised Fog nodes
- · coordinated / stealthy attacks

Validate trust dynamics

- · Does the evolutionary game penalize malicious nodes?
- Does the trust-weighted GNN reduce their influence?

Compare against baselines

- Flat IDS
- · Horizontal-only GNN
- · GNN without trust adaptation

SIMULATING ADVERSARIAL BEHAVIOUR IN IOT FOG NETWORKS

Scenario 1 – Lowlevel corruption: 10% of Fog nodes generate systematic false alerts. Scenario 2 – Mixed malicious activity: 20% of nodes behave maliciously and inject random noise into their reports.

Scenario 3 –
Coordinated
adversaries:
A group of Fog nodes
cooperates to mimic
legitimate patterns
while pushing false
information.

Goal: Stress-test the trust mechanism under realistic and stealthy adversarial conditions.

DATASET AND SIMULATION PARAMETERS

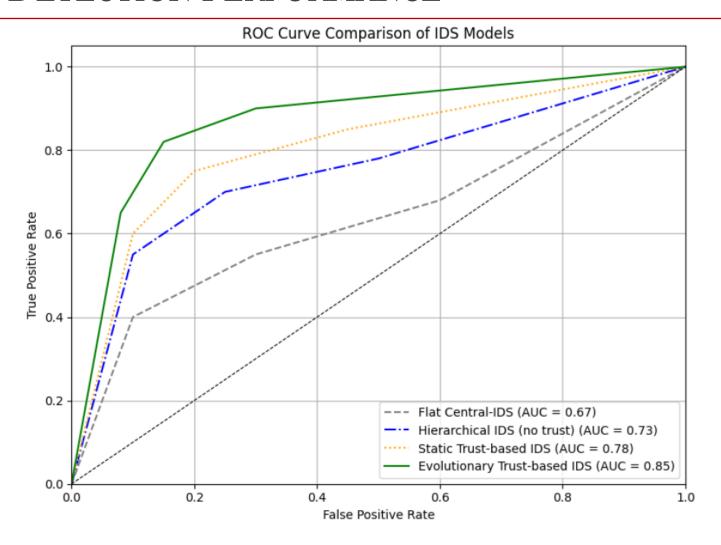
Dataset: UNSW-NB15 (2.5M records, 9 attack categories).

IoT environment: 3-tier **Edge** → **Fog** → **Cloud** topology.

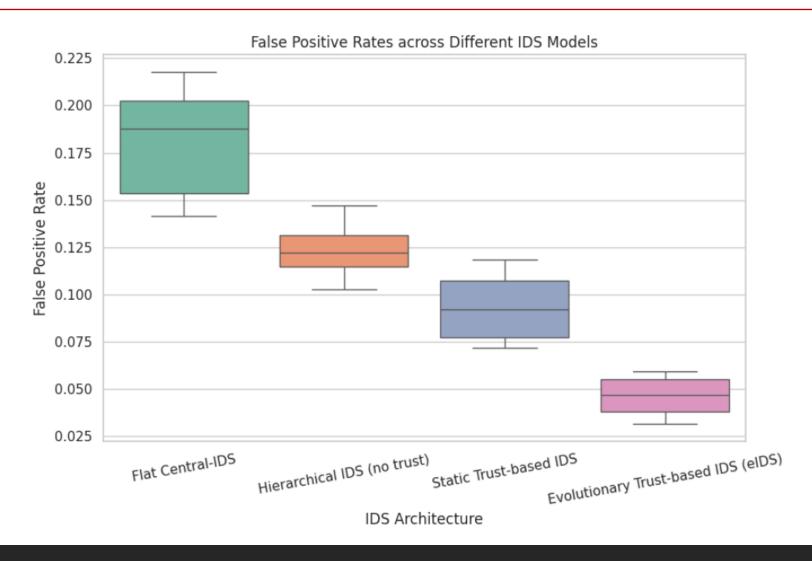
Implementation: PyTorch + PyTorch-Geometric, 50 epochs, Adam optimizer.

Evaluation focus: accuracy **and** resilience under adversarial stress.

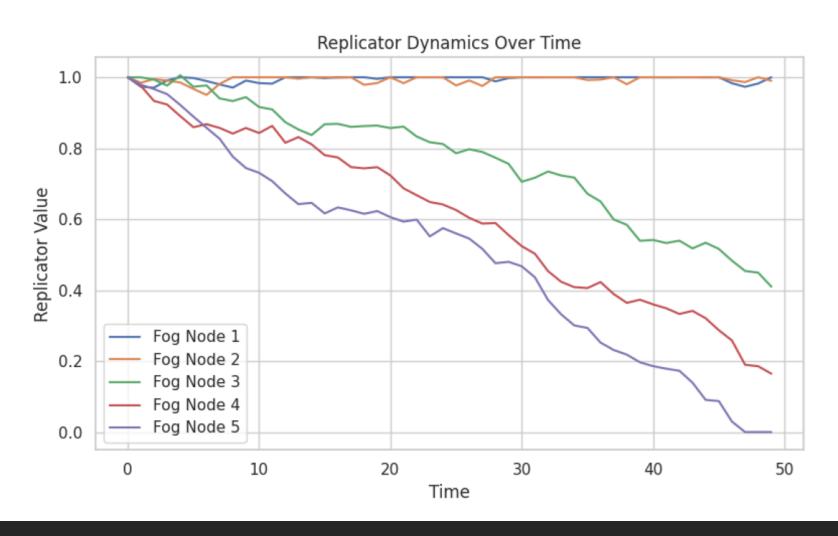
GLOBAL DETECTION PERFORMANCE



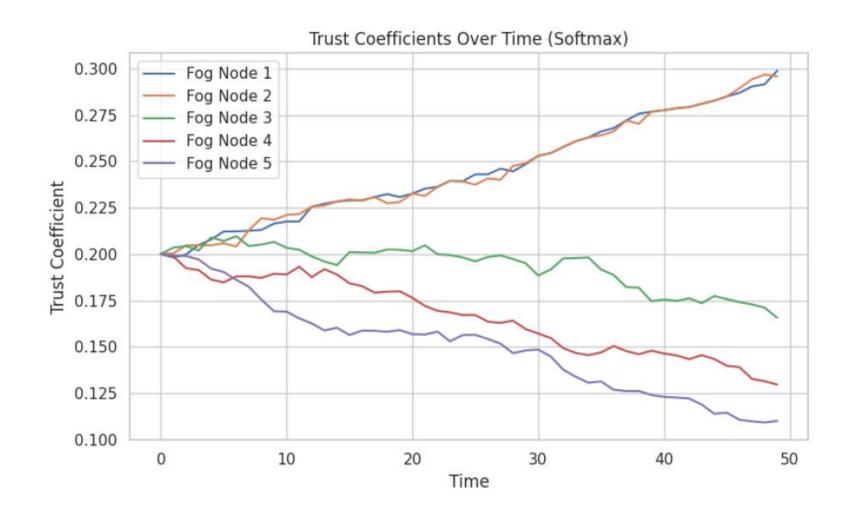
REDUCING FALSE ALARMS THROUGH ADAPTIVE TRUST



HOW TRUST EMERGES OVER TIME



Trust Convergence Across Fog Nodes



CONCLUSION AND FUTURE WORK

Toward Adaptive & Trust-Aware IDS for IoT

V-IDS provides multi-layer intrusion detection with evolving trust.

Combining GNN + Evolutionary Games improves robustness under adversarial drift.

Next steps: Edge-Fog-Cloud deployment, scalability experiments, federated trust learning.



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Thank You! Questions?

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